

Feed Sideward

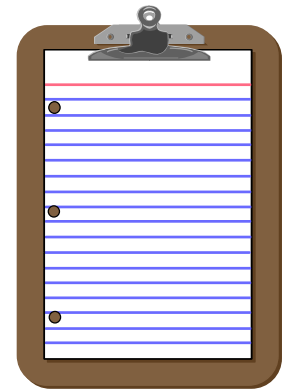
Understanding Biological Rhythms



Jim Holte

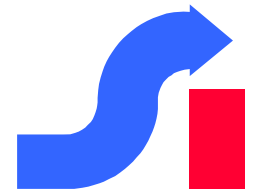
1/15/2002

Sessions



- • Session 1 - Feed Sideward – Concepts and Examples, *1/15*
- Session 2 – Feed Sideward – Applications to Biological & Biomedical Systems, *1/31*
 - Session 3 – Chronobiology, *2/12*
Franz Hallberg and Germaine Cornalissen

Feed Sideward

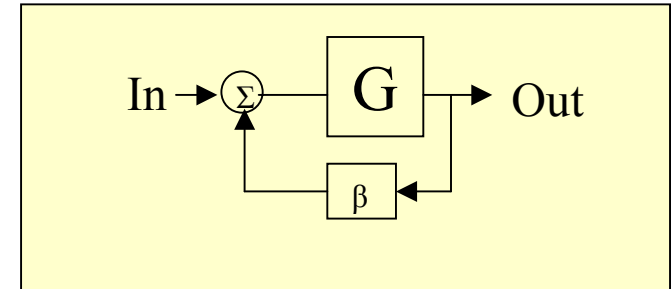


Terms

- Feed Back

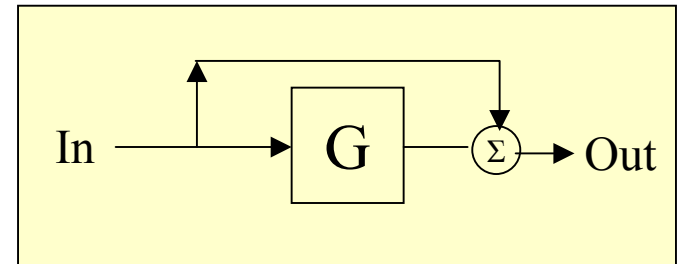
Simple Example

Reinvesting dividends



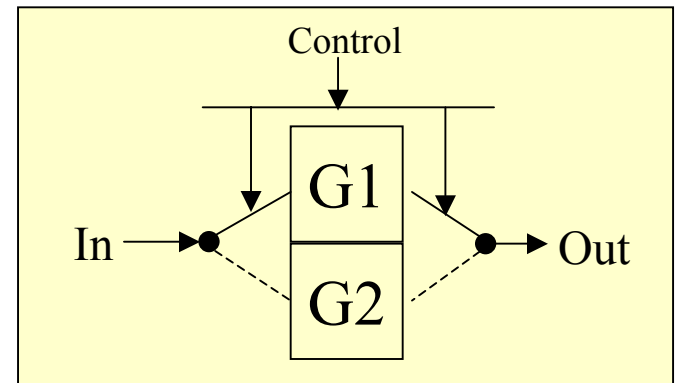
- Feed Forward

Setting money aside

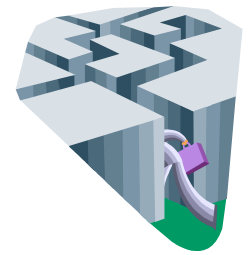


- Feed Sideward

Moving money to another account



Introduction

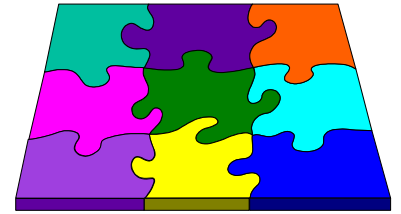


Feed Sideward is a coupling that shifts resources from one subsystem to another

- Feed Sideward #1 – feeds ***values of other variables*** into the specified variable
- Feed Sideward #2 – feeds ***changes of parameters*** into the specified variable. (time varying parameters)
- Feed Sideward #3 – feeds ***changes of topology*** by switch operations (switched systems)

Tool for global analysis
especially useful for biological systems

Phase Space



- Laws of the physical world
- Ordinary differential equations
- Visualization of Solutions
- Understanding

Phase Space



The Lotka-Volterra Equations for
Predator-Prey Systems

$$H' = b \cdot H - a \cdot H \cdot P$$

$$P' = -d \cdot P + c \cdot H \cdot P$$

H = prey abundance, P = predator

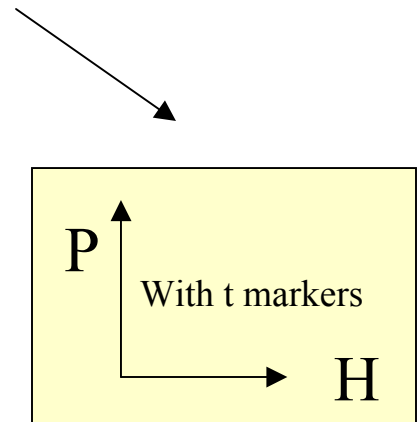
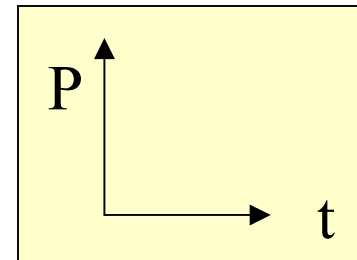
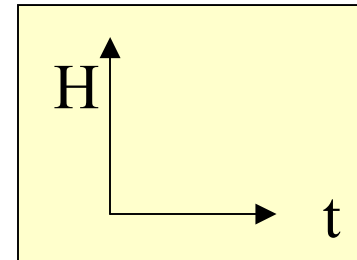
Set the parameters

$b = 2$ growth coefficient of prey

$d = 1$ growth coefficient of
predators

$a = 1$ rate of capture of prey per
predator per unit time

$c = 1$ rate of "conversion" of prey
to predators per unit time
per predator.



Source: ODE Architect, Wiley, 1999

Phase Space

The Lotka-Volterra Equations for
Predator-Prey Systems

$$H' = b \cdot H - a \cdot H \cdot P$$

$$P' = -d \cdot P + c \cdot H \cdot P$$

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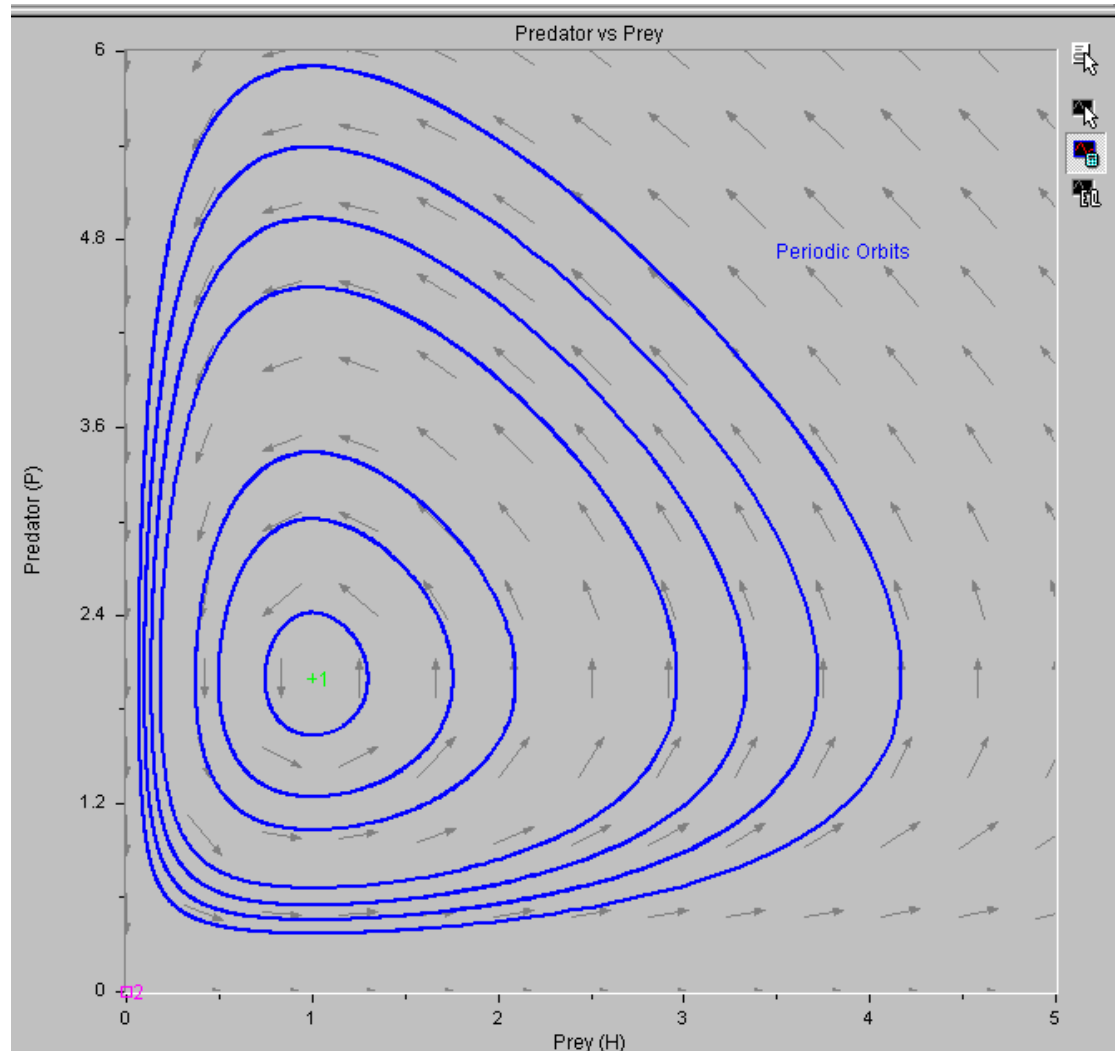
Set the parameters

b = 2 growth coefficient of prey

d = 1 growth coefficient of
predators

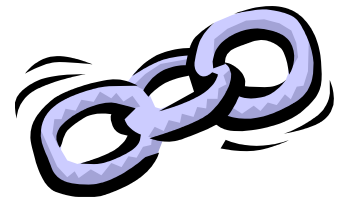
a = 1 rate of capture of prey per
predator per unit time

c = 1 rate of "conversion" of prey
to predators per unit time
per predator.



Source: *ODE Architect*, Wiley, 1999

Coupled Oscillators Model



- x and y represent the "phases" of two oscillators.

Think of x and y :

- angular positions of two "particles"
 - moving around the unit circle
- $a_1 = 0$
 - x has constant angular rate
 - $a_2 = 0$
 - y has constant angular rate.
 - Coupling when a_1 or a_2 non-zero

Source: ODE Architect, Wiley, 1999

Example

Uncoupled Oscillators

The Tortoise and the Hare

$$x' = w1 + a1 * \sin(y - x)$$

$$y' = w2 + a2 * \sin(x - y)$$

$u = (x \bmod(2 * \pi))$ //Wrap around the

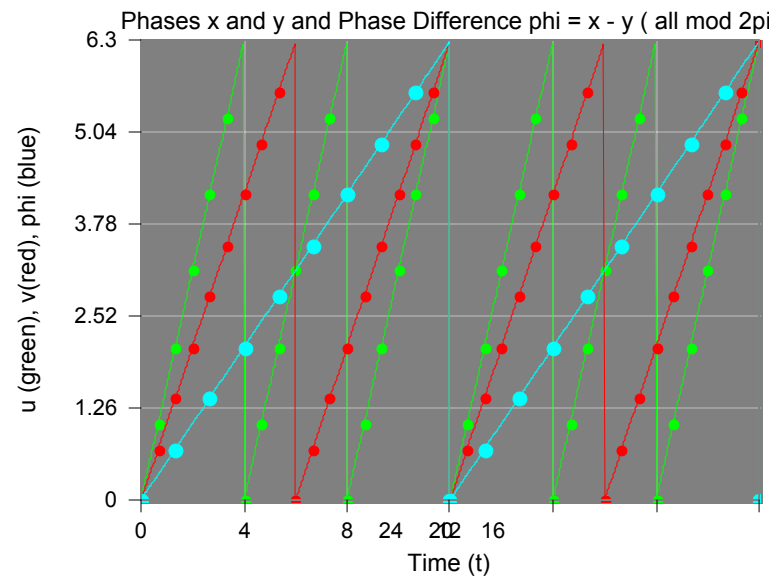
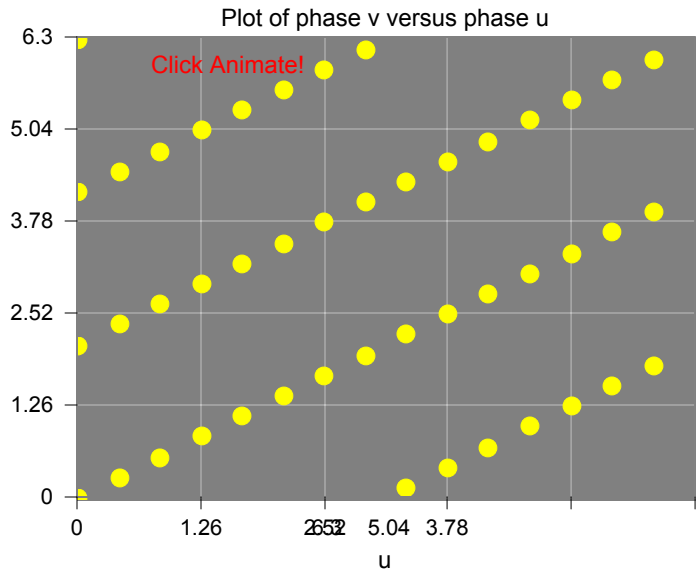
$v = (y \bmod(2 * \pi))$ //unit circle

$\phi = (x - y) \bmod(2 * \pi)$

Set the parameters

$a1 = 0.0$; $a2 = 0.0$

$w1 = \pi/2$; $w2 = \pi/3$



Source: *ODE Architect*, Wiley, 1999

Example

Coupled Oscillators

Coupled Oscillators:

The Tortoise and the Hare

$$x' = w1 + a1 * \sin(y - x)$$

$$y' = w2 + a2 * \sin(x - y)$$

$$u = (x \bmod(2 * \pi)) \text{ // Wrap around the}$$

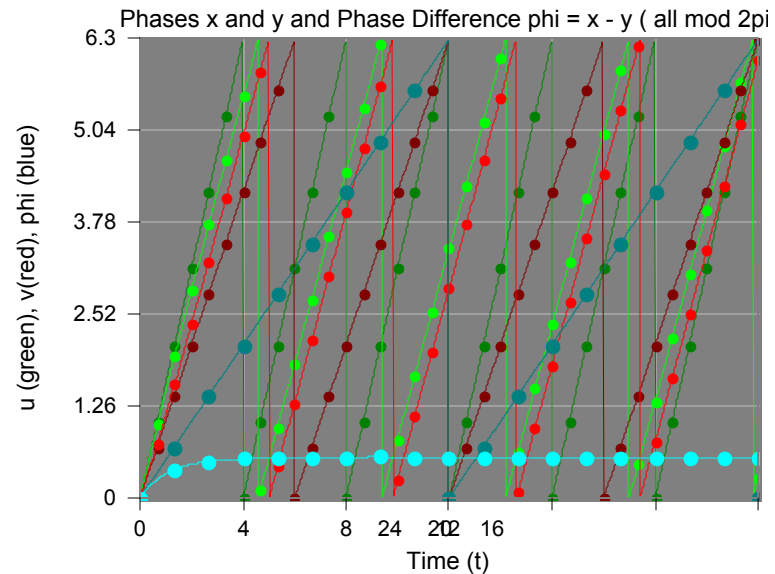
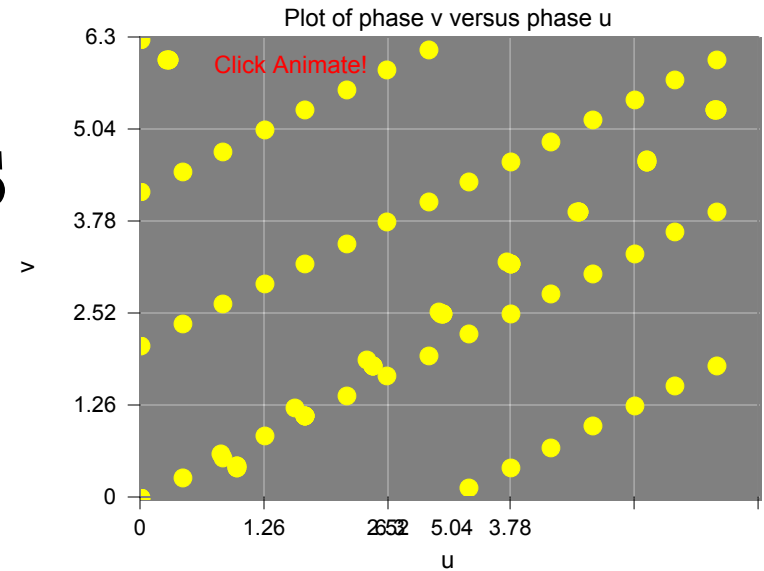
$$v = (y \bmod(2 * \pi)) \text{ // unit circle}$$

$$\phi = (x - y) \bmod(2 * \pi)$$

Set the parameters

$$a1 = 0.5; a2 = 0.5$$

$$w1 = \pi/2; w2 = \pi/3$$



Source: *ODE Architect*, Wiley, 1999

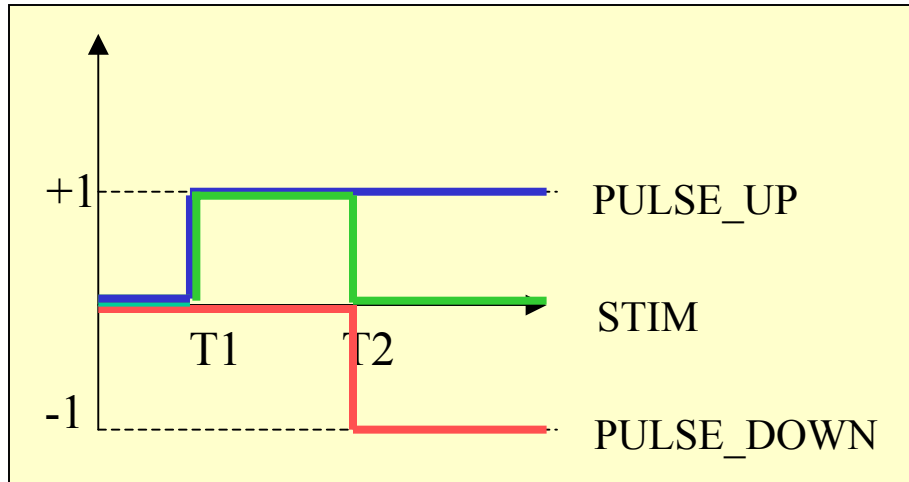
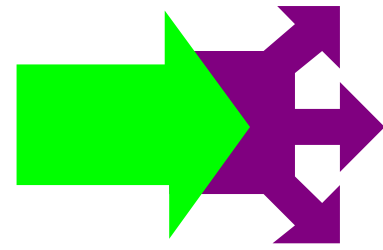
Jim Holte

University of Minnesota

1/15/02

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Phase Resetting



```
FUNCTION PULSE_UP(t, T1, STIM_H)  
IF (t >= T1) THEN  
  PULSE_UP = STIM_H  
ELSE  
  PULSE_UP = 0  
ENDIF  
RETURN PULSE_UP  
END
```

```
FUNCTION STIM(t,T1,T2,STIM_L,STIM_H)
```

```
STIM = PULSE_UP(t, T1, STIM_H) +  
PULSE_DOWN(t, T2, STIM_L)
```

```
RETURN STIM
```

```
END
```

```
FUNCTION PULSE_DOWN(t,T2,STIM_L)
```

```
IF (t <= T2) THEN  
  PULSE_DOWN = 0  
ELSE  
  PULSE_DOWN = STIM_L  
ENDIF  
RETURN PULSE_DOWN  
END
```

Example

Phase Resetting

$$\Theta' = 1 + \text{STIM}(t, T1, T2, \text{STIM_L}, \text{STIM_H}) * \cos(2 * \Theta)$$

$$T1 = 4$$

$$T2 = 4$$

$$\text{STIM_L} = -1$$

$$\text{STIM_H} = +1$$

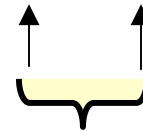
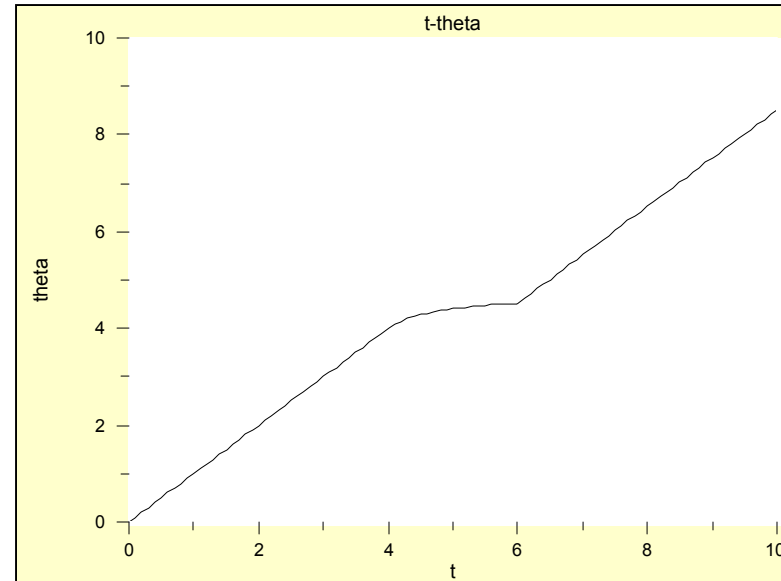
$$\Theta' = 1 + \text{STIM}(t, T1, T2, \text{STIM_L}, \text{STIM_H}) * \cos(2 * \Theta)$$

$$T1 = 4$$

$$T2 = 6$$

$$\text{STIM_L} = -1$$

$$\text{STIM_H} = +1$$



Source: *ODE Architect*, Wiley, 1999

Oscillator Entrainment



- x and y represent the "phases" of two oscillators.

Think of x and y :

- angular positions of two "particles"
- moving around the unit circle
- $a_1 = 0$
 - x has constant angular rate
- $a_2 = 0$
 - y has constant angular rate.
- Coupling when a_1 & a_2 non-zero

- Entrainment occurs when the **coupling causes**
 - angular rate of x to
 - approach angular rate of y
- x and y generally differ
 - Typical for Chronobiology
- Dominant oscillator **'entrains'** the other

Source: ODE Architect, Wiley, 1999

Oscillator Entrainment

Example

$$x' = w1 + a1 * \sin(y - x)$$

$$y' = w2 + a2 * \sin(x - y)$$

$$u = (x \bmod(2 * \pi)) \text{ // Wrap around the}$$

$$v = (y \bmod(2 * \pi)) \text{ // unit circle}$$

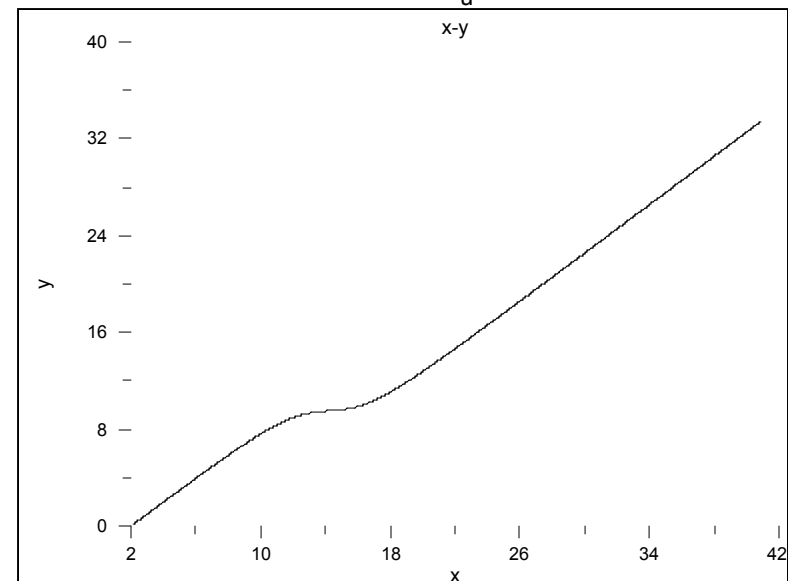
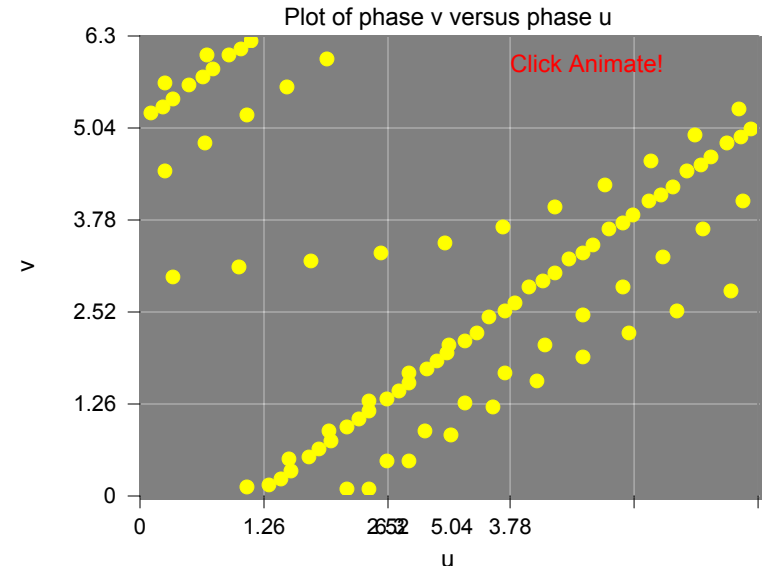
$$\text{phi} = (x - y) \bmod(2 * \pi)$$

Set the parameters

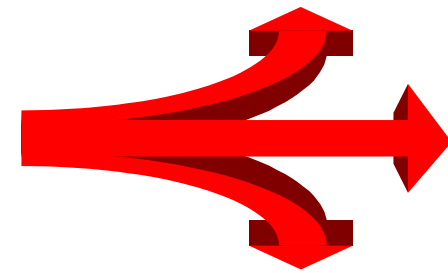
$$a1 = .0775 * \pi; a2 = .075 * \pi$$

$$w1 = \pi/4; w2 = \pi/4 - .14 * \pi$$

Source: *ODE Architect*, Wiley, 1999



Singularities



$$r' = -(r-0)*(r-1/2)*(r-1) - a*STIM(t,T1,T2,STIM_L,STIM_H)$$

$$\text{theta}' = 1$$

$$x = r*\cos(\text{theta})$$

$$y = r*\sin(\text{theta})$$

$$T1 = 4$$

$$T2 = 6$$

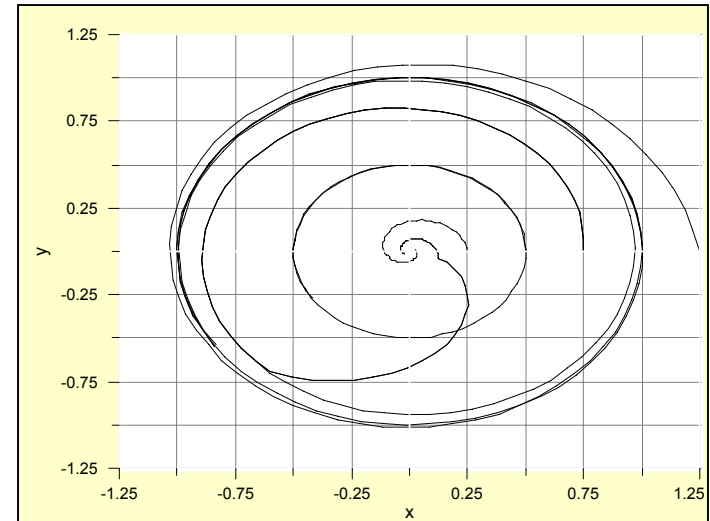
$$a=0.0$$

$$STIM_L = -1$$

$$STIM_H = +1$$

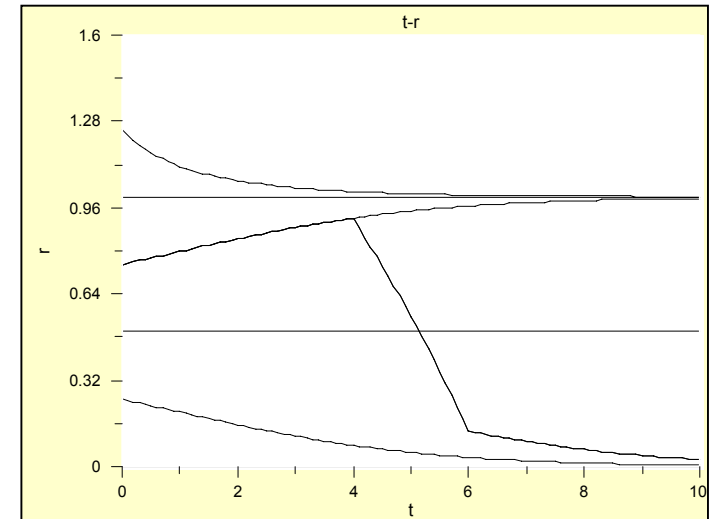
Example - Singularities

Run	r	a	Comment
---	---	---	-----
#1	1.25	0	approaches $r=1$
#2	1.0	0	stable periodic orbit
#3	0.75	0	approaches $r=1$
#4	0.5	0	unstable periodic orbit
#5	0.25	0	approaches $r=0$
#6	0	0	stable periodic orbit
#7	0.75	0.4	starts in $r=1$ domain, STIM moves it to $r=0$ domain

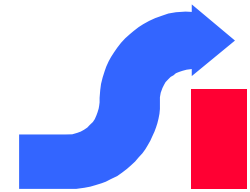


$r' = -(r-0)*(r-1/2)*(r-1) - a*STIM(t,T1,T2,STIM_L,STIM_H)$
 $\theta' = 1$
 $x = r*\cos(\theta)$
 $y = r*\sin(\theta)$

$T1 = 4$
 $T2 = 6$
 $a = 0.0$
 $STIM_L = -1$
 $STIM_H = +1$



Feed Sideward

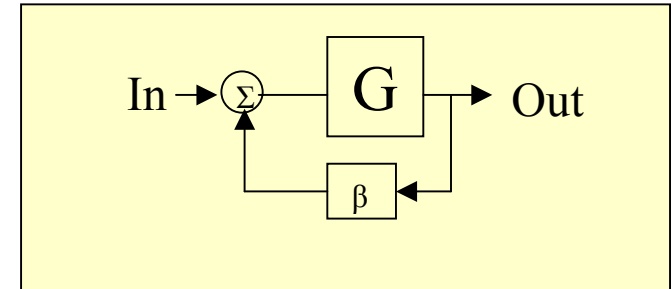


Terms

- Feed Back

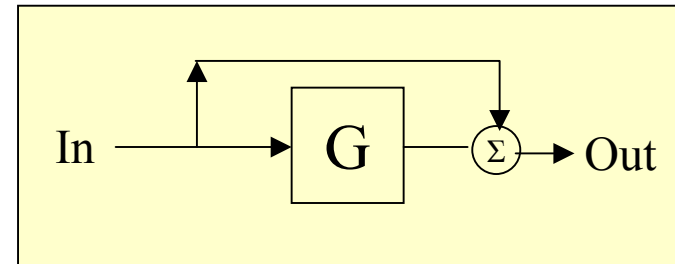
Simple Example

Reinvesting dividends



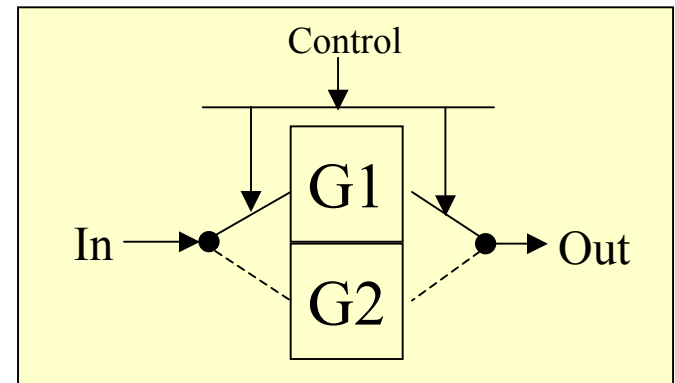
- Feed Foreward

Setting money aside



- Feed Sideward

Moving money to another account



Feed Sideward Example

The Oregonator Model for Chemical Oscillations

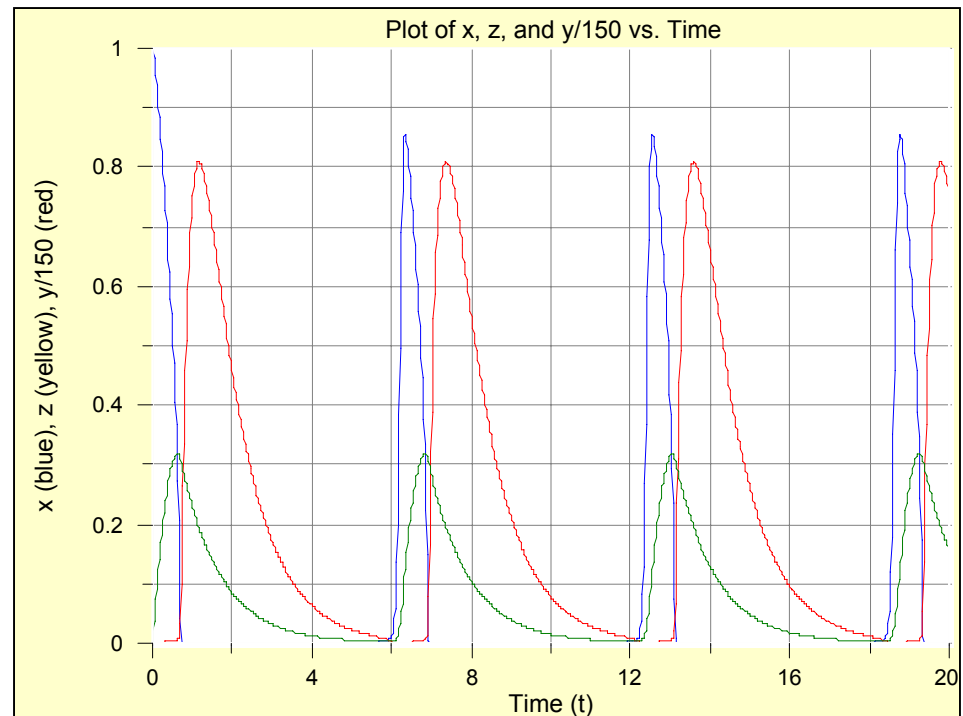
$$x' = a1*(a3*y - x*y + x*(1-x))$$

$$y' = a2*(-a3*y - x*y + f*z)$$

$$z' = x - z$$

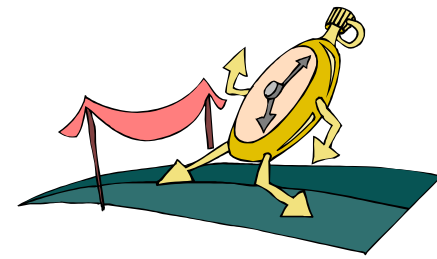
$$\text{smally} = y/150$$

$$a1 = 25; a3 = 0.0008; a2 = 2500; f = 1$$



Source: *ODE Architect*, Wiley, 1999

Summary

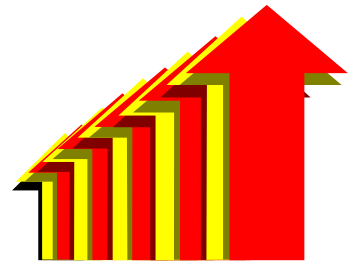


Feed Sideward is a coupling that shifts resources from one subsystem to another

- Feed Sideward #1 – feeds ***values of other variables*** into the specified variable
- Feed Sideward #2 – feeds ***changes of parameters*** into the specified variable. (time varying parameters)
- Feed Sideward #3 – feeds ***changes of topology*** by switch operations (switched systems)

Tool for global analysis
especially useful for biological systems

Next Session



- Session 1 - Feed Sideward – Concepts and Examples, *1/15*
- • Session 2 – Feed Sideward – Applications to Biological & Biomedical Systems, *1/31*
- Session 3 – Chronobiology, *2/12*
Franz Hallberg and Germaine Cornelissen

Backup

Feed Sideward - Topics (60 min)

Session 1 (14 slides)

- Background Concepts & Examples
 - Phase Space (1 slide)
 - Singularities (2 slides) *
 - Coupled Oscillators (2 slides)
 - Phase Resetting (2 slides) *
 - Oscillator Entrainment (1 slide)
- Feed Sideward as modulation (3 slides) **
- Summary (1 slide)

Session 2 (12 slides)

- Applications to Biological Systems
 - Circadian & other Rhythms (2 slides)
 - Model & Simulation Result (2 slides)
- Applications to Biomedical Systems
 - Blood Pressure Application (2 slides)
 - Model & Simulation Result (2 slides)
- Summary (1 slide)
- Segue to Chronobiology (1 slide)